

Green Integrals on Manifolds with Cracks

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May 29, 2000

^{*}Supported by the Max-Planck Gesellschaft and the RFFI grant 99-01-00790.

Abstract

We prove the existence of a limit in $H^m(D)$ of iterations of a double layer potential constructed from the Hodge parametrix on a smooth compact manifold with boundary, X , and a crack $S \subset \partial D$, D being a domain in X . Using this result we obtain formulas for Sobolev solutions to the Cauchy problem in D with data on S , for an elliptic operator A of order $m \geq 1$, whenever these solutions exist. This representation involves the sum of a series whose terms are iterations of the double layer potential. A similar regularisation is constructed also for a mixed problem in D .

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1 Introduction

This paper is based on the following simple observation. Consider an operator equation $Au = f$ with a bounded operator $A: H_0 \rightarrow H_1$ in Hilbert spaces. Suppose each element $u \in H_0$ can be written in the form $u = \pi_0 u + \pi_1 Au$ where π_0 is a projection onto the kernel of A in H_0 . Then it is to be expected that under reasonable conditions the element $\pi_1 f$ defines a solution to the equation $Au = f$.

For the Cauchy-Riemann operator $A = \bar{\partial}$ in \mathbb{C}^n , $n > 1$, the double layer potential involved in the regularisation formula is just the Martinelli-Bochner integral. In this case, results similar to ours were obtained by Romanov [6].

Theorem 1.1 *Let D be a bounded domain in \mathbb{C}^n , $n > 1$, with a connected boundary of class C^1 , and Mu stand for the Martinelli-Bochner integral of a function $u \in H^1(D)$. Then the limit $\lim_{N \rightarrow \infty} M^N$ exists in the strong operator topology of $H^1(D)$, and it is equal to π_0 , a projection onto the (closed) subspace of holomorphic functions in $H^1(D)$.*

By using this result Romanov [6] obtained an explicit formula for a solution $u \in H^1(D)$ to $\bar{\partial}u = f$, where D is a pseudoconvex domain with a smooth boundary, and f a $\bar{\partial}$ -closed $(0, 1)$ -form with coefficients in $H^1(D)$.

2 Preliminary results

Let X be a C^∞ manifold of dimension n with a smooth boundary ∂X . We tacitly assume that it is enclosed into a smooth closed manifold \tilde{X} of the same dimension.

For any smooth \mathbb{C} -vector bundles E and F over X , we write $\text{Diff}^m(X; E, F)$ for the space of all linear partial differential operators of order $\leq m$ between sections of E and F .

Denote E^* the conjugate bundle of E . Any Hermitian metric $(\cdot, \cdot)_x$ on E gives rise to a sesquilinear bundle isomorphism $*_E: E \rightarrow E^*$ by the equality $\langle *_E v, u \rangle_x = (u, v)_x$ for all sections u and v of E .

Pick a volume form dx on X , thus identifying dual and conjugate bundles. For $A \in \text{Diff}^m(X; E, F)$, denote by $A' \in \text{Diff}^m(X; F^*, E^*)$ the transposed operator and by $A^* \in \text{Diff}^m(X; F, E)$ the formal adjoint operator. We obviously have $A^* = *_E^{-1} A' *_F$, cf. [9, 4.1.4] and elsewhere.

For an open set $O \subset X$, we write $L^2(O, E)$ for the Hilbert space of all measurable sections of E over O with a finite norm $(u, u)_{L^2(O, E)} = \int_O (u, u)_x dx$. When no confusion can arise, we also denote $H^m(O, E)$ the Sobolev space of distribution sections of E over O , whose weak derivatives up to order m belong to $L^2(O, E)$.

Given any open set O in $\overset{\circ}{X}$, the interior of X , we let $\mathcal{S}_A(O)$ stand for the space of weak solutions to the equation $Au = 0$ in O . We also denote by $\mathcal{S}_A^m(O)$ the closed subspace of $H^m(O, E)$ consisting of all weak solutions to $Au = 0$ in O .

Write $\sigma(A)$ for the principal homogeneous symbol of order m of the operator A , $\sigma(A)$ living on the cotangent bundle T^*X of X . From now on we assume that $\sigma(A)$ is injective away from the zero section of T^*X . Hence it follows that the Laplacian $\Delta = A^*A$ is an elliptic differential operator of order $2m$ on X .

Let σ be a compact subset in $\overset{\circ}{X}$. In fact, we assume that σ lies on a smooth closed hypersurface S in X . Our goal will be to construct the Hodge theory of the Dirichlet problem for the Laplacian Δ on the manifold $V = \overset{\circ}{X} \setminus \sigma$ with a crack along σ .

Crack problems are usually treated in the framework of analysis on manifolds with edges, cf. Schulze [7]. One thinks of the boundary of σ on S as an edge of V , the cross-section being a 2-dimensional plane with a cut along a ray. The relevant function spaces are therefore weighted Sobolev spaces $H^{s,w}((V, \partial\sigma), E)$ of smoothness s and weight w , both s and w being real numbers. Recall that if $s \in \mathbb{Z}_+$ it coincides with the completion of sections of E over V , C^∞ up to the boundary and vanishing near $\partial\sigma$, with respect to the norm

$$\|u\|_{H^{s,w}((V, \partial\sigma), E)} = \left(\sum_{\nu} \int \sum_{|\alpha| \leq s} \text{dist}(x, \partial\sigma)^{2(|\alpha| - w)} |D^\alpha(\varphi_\nu u)|^2 dx \right)^{1/2},$$

where (φ_ν) is a partition of unity subordinate to a suitable finite open covering (O_ν) of X .

However, we will deal with the very particular case $H^{m,m}((V, \partial\sigma), E)$ which allows us to restrict ourselves to the usual Sobolev spaces on X .

Namely, let $H^m((V, \partial\sigma), E)$ be the closure of all sections of E over V , C^∞ up to the boundary and vanishing close to $\partial\sigma$, in $H^m(V, E)$.

Theorem 2.1 *If the boundary of σ is smooth, then $H^{m,m}((V, \partial\sigma), E)$ and $H^m((V, \partial\sigma), E)$ coincide as topological vector spaces.*

Proof. Obviously, it is sufficient to show that the $H^{m,m}((V, \partial\sigma), E)$ - and $H^m(V, E)$ -norms are equivalent on sections of E over V , C^∞ up to the boundary and vanishing close to $\partial\sigma$. Without loss of generality we can consider those sections u whose supports are contained in the domain O_ν of some chart on X .

If O_ν does not meet $\partial\sigma$ then $\text{dist}(x, \partial\sigma)$ is strictly positive in O_ν . Hence the $H^{m,m}((V, \partial\sigma), E)$ - and $H^m(V, E)$ -norms are equivalent on sections of E with a support in O_ν .

In the case $O_\nu \cap \partial\sigma \neq \emptyset$ we choose local coordinates $x = (x_1, \dots, x_n)$ in O_ν , such that $O_\nu \cap \sigma$ is the half-plane $\{x_n = 0, x_{n-1} \leq 0\}$. Write $x = (x', x_{n-1}, x_n)$ where $x' = (x_1, \dots, x_{n-2})$. We restrict ourselves to sections $u = u(x', x_{n-1}, x_n)$ supported in $Q \times B$, with Q a rectangle in \mathbb{R}^{n-2} , and B a disk with centre 0 and radius $R \gg 1$.

Since

$$\|u\|_{H^{m,m}((V,\partial\sigma),E)}^2 = \int \sum_{|\alpha| \leq m} \text{dist}(x, \partial\sigma)^{2(|\alpha|-m)} |D^\alpha u|^2 dx,$$

the $H^m(V, E)$ -norm is obviously dominated by the $H^{m,m}((V, \partial\sigma), E)$ -norm whence

$$H^{m,m}((V, \partial\sigma), E) \hookrightarrow H^m((V, \partial\sigma), E).$$

On the other hand, the summands involving the derivatives of order m in the norms $\|u\|_{H^{m,m}((V,\partial\sigma),E)}$ and $\|u\|_{H^m(V,E)}$ coincide. To handle lower order summands, we fix a multi-index $\alpha \in \mathbb{Z}_+^n$ with $0 \leq |\alpha| \leq m-1$. Introduce polar coordinates

$$\begin{cases} x_{n-1} &= r \cos \varphi, \\ x_n &= r \sin \varphi \end{cases}$$

in B , and set $U(r) = D^\alpha u(x', r \cos \varphi, r \sin \varphi)$. Then

$$\int \text{dist}(x, \partial\sigma)^{2(|\alpha|-m)} |D^\alpha u|^2 dx = \int_Q dx' \int_{-\pi}^{\pi} d\varphi \int_0^R |r^{|\alpha|-m} U(r)|^2 r dr.$$

We next make use of a Hardy-Littlewood inequality for measurable functions on the semiaxis with values in a normed space. Namely,

$$\|r^{p-1} \int_0^r f(\varrho) d\varrho\|_{L^q(\mathbb{R}_+)} \leq \left(\frac{1}{q'} - p\right)^{-1} \|r^p f(r)\|_{L^q(\mathbb{R}_+)},$$

where $1 \leq q \leq \infty$, $1/q + 1/q' = 1$ and $p < 1/q'$. Take $f(r) = (\partial/\partial r)U(r)$ and observe that

$$\begin{aligned} |f'(r)| &= |D^{\alpha+1_{n-1}} u \cos \varphi + D^{\alpha+1_n} u \sin \varphi| \\ &\leq |D^{\alpha+1_{n-1}} u| + |D^{\alpha+1_n} u|, \end{aligned}$$

1_j being the multi-index from \mathbb{Z}_+^n which is 1 in the j -th place and 0 in each other one. Repeated application of the Hardy-Littlewood inequality therefore yields

$$\int \text{dist}(x, \partial\sigma)^{2(|\alpha|-m)} |D^\alpha u|^2 dx \leq c \|D^\alpha u\|_{H^{m-|\alpha|}(V,E)}^2,$$

with c a constant independent of u .

Summarising we conclude that the $H^{m,m}((V, \partial\sigma), E)$ -norm is majorised by the $H^m(V, E)$ -norm on functions vanishing near $\partial\sigma$. This completes the proof. \square

More generally, given an open set $O \subset X$ and a closed set $\sigma \subset X$, we denote $H^m((O, \sigma), E)$ the closure of all sections of E over O , C^∞ up to the boundary and vanishing near σ , in $H^m(O, E)$. If $\sigma = \partial O$, we obtain what is usually referred to as

$$\mathring{H}^m(O, E).$$

Fix a Dirichlet system B_j , $j = 0, 1, \dots, m-1$, of order $m-1$ on the boundary of V . More precisely, each B_j is a differential operator of type $E \rightarrow F_j$ and order $m_j \leq m-1$ in a neighbourhood U of $\partial X \cup S$. Moreover, the symbols $\sigma(B_j)$, if restricted to the conormal bundle of $\partial X \cup S$, have ranks equal to the dimensions of F_j .

Set $t(u) = \bigoplus_{j=0}^{m-1} B_j u$, for $u \in H^m(V, E)$. It follows from the results of Hedberg [1] that

$$\mathring{H}^m(V, E) = \{u \in H^m(X, E) : t(u) = 0 \text{ on } \partial X \cup \sigma\}, \quad (2.1)$$

$\partial X \cup \sigma$ being the boundary of V .

Corollary 2.2 *Suppose $\partial\sigma$ is smooth. Then we have a topological isomorphism*

$$\mathring{H}^m(V, E) \cong \{u \in H^{m,m}((V, \partial\sigma), E) : t(u) = 0 \text{ on } \partial X \cup \mathring{\sigma}\},$$

the space on the right-hand side being endowed with the norm induced from $H^{m,m}((V, \partial\sigma), E)$.

Proof. By Theorem 2.1 it suffices to show that $\mathring{H}^m(V, E)$ consists of all $u \in H^m((V, \partial\sigma), E)$ such that $t(u) = 0$ on ∂V .

On the one hand, if $u \in \mathring{H}^m(V, E)$ then $u \in H^m((V, \partial\sigma), E)$ and $t(u) = 0$ on ∂V , as is easy to see.

On the other hand, if $u \in H^m((V, \partial\sigma), E)$ and $t(u) = 0$ on ∂V then $u \in H^m((V, \partial V), E)$, as follows from [1]. This just amounts to the desired assertion. \square

3 Hodge theory on manifolds with cracks

Let $H^{-m}(V, E)$ denote the dual space of $\mathring{H}^m(V, E)$ with respect to the pairing in $L^2(V, E)$. This is not a canonical definition, we rather follow the notation of [9, 1.4.9].

For every $u \in H^m(V, E)$, the correspondence

$$v \mapsto \int_V (Au, Av)_x dx$$

is a continuous conjugate linear functional on $\mathring{H}^m(V, E)$. Thus, the Laplacian $\Delta = A^*A$ extends to a mapping $H^m(V, E) \rightarrow H^{-m}(V, E)$.

The following boundary value problem is a straightforward generalisation of the classical Dirichlet problem, cf. [9, 9.2.4].

Problem 3.1 *Given an $F \in H^{-m}(V, E)$, find a section $u \in H^m(X, E)$ such that*

$$\begin{cases} \Delta u &= F & \text{in } V, \\ t(u) &= 0 & \text{on } \partial V. \end{cases}$$

Another way of stating the problem is to say, “Study the restriction of Δ to $\mathring{H}^m(V, E)$.”

If $u \in \mathring{H}^m(V, E)$ and $\Delta u = 0$, then $Au = 0$ in V . In the sequel, $\mathcal{H}(V)$ stands for

$$\mathring{H}^m(V, E) \cap \mathcal{S}_A(V).$$

Furthermore, we let $\mathcal{H}^\perp(V)$ consist of all sections $F \in H^{-m}(V, E)$ satisfying

$$\int_V (F, v)_x dx = 0$$

for any $v \in \mathcal{H}(V)$.

Lemma 3.2 *Problem 3.1 is Fredholm. The difference of any two solutions lies in $\mathcal{H}(V)$. The problem is solvable if and only if $F \in \mathcal{H}^\perp(V)$. Moreover, there is a constant $c > 0$ such that for any solution $u \in \mathcal{H}^\perp(V)$ to Problem 3.1, we have*

$$\|u\|_{H^m(X, E)} \leq c \|F\|_{H^{-m}(V, E)}. \quad (3.1)$$

Proof. By definition, the equality $\Delta u = F$ means that

$$\int_V (Au, Av)_x dx = \int_V (F, v)_x dx \quad (3.2)$$

for all $v \in \mathring{H}^m(V, E)$. We are thus looking for a section $u \in \mathring{H}^m(V, E)$ satisfying (3.2).

It readily follows from (3.2) that the null-space of Problem 3.1 is just $\mathcal{H}(V)$. Since

$$\mathring{H}^m(V, E) \hookrightarrow H^m(X, E)$$

and σ is a set of zero measure in $\overset{\circ}{X}$, we deduce that

$$\mathcal{H}(V) \hookrightarrow \dot{H}^m(\overset{\circ}{X}, E) \cap \mathcal{S}_A(\overset{\circ}{X}),$$

the space on the right-hand side being $\mathcal{H}(\overset{\circ}{X})$. Taking into account that the boundary of X is smooth, we deduce that $\mathcal{H}(V)$ is a finite-dimensional subspace of $C^\infty(X, E)$.

That the condition $F \in \mathcal{H}^\perp(V)$ is necessary for the problem to be solvable, follows from (3.2) immediately. Let us prove the sufficiency.

To this end, we invoke the classical Gårding inequality. Namely, as A has injective symbol, we have

$$\|u\|_{H^m(X, E)}^2 \leq C \int_X (Au, Au)_x dx + c \|u\|_{L^2(X, E)}^2 \quad (3.3)$$

for all $u \in \dot{H}^m(V, E)$, the constants C and c being independent of u (cf. for instance [10]).

A familiar argument shows that there is a constant $C > 0$ with the property that

$$\|u\|_{H^m(X, E)}^2 \leq C \int_X (Au, Au)_x dx,$$

for each $u \in \dot{H}^m(V, E) \cap \mathcal{H}^\perp(V)$. Indeed, we argue by contradiction. If there is no such constant then we can find a sequence (u_ν) in $\dot{H}^m(V, E) \cap \mathcal{H}^\perp(V)$, such that

$$\begin{aligned} \|u_\nu\|_{H^m(X, E)} &= 1, \\ \|Au_\nu\|_{L^2(X, F)} &< 2^{-\nu}. \end{aligned}$$

As the unit ball in a separable Hilbert space is weakly compact, we can assume that (u_ν) converges weakly to a section $u_\infty \in \dot{H}^m(V, E) \cap \mathcal{H}^\perp(V)$. It follows that

$$\begin{aligned} \int_X (u_\infty, A^*v)_x dx &= \lim_{\nu \rightarrow \infty} \int_X (u_\nu, A^*v)_x dx \\ &= \lim_{\nu \rightarrow \infty} \int_X (Au_\nu, v)_x dx \\ &= 0 \end{aligned}$$

for all $v \in C_{\text{comp}}^\infty(\overset{\circ}{X}, E)$, i.e. $u_\infty \in \mathcal{H}(V)$. We thus conclude that $u_\infty = 0$. But the Gårding inequality yields

$$1 \leq C 2^{-\nu} + c \|u_\nu\|_{L^2(X, E)}$$

for all ν . Since the inclusion $\mathring{H}^m(V, E) \hookrightarrow L^2(X, E)$ is compact, and thus u_ν converges strongly to u_∞ in $L^2(X, E)$, we get

$$\|u_\infty\|_{L^2(X, E)} \geq 1/c,$$

which contradicts $u_\infty = 0$.

We have thus proved that the Hermitian form

$$\int_X (Au, Av)_x dx$$

defines a scalar product in the Hilbert space $\mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V)$, the corresponding norm being equivalent to the original one. Now the Riesz Theorem enables us to assert that for every $F \in H^{-m}(V, E)$ there exists a unique section

$$u \in \mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V)$$

satisfying

$$\int_V (F, v)_x dx = \int_X (Au, Av)_x dx$$

for all $v \in \mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V)$.

Obviously, every $v \in \mathring{H}^m(V, E)$ can be written in the form $v = v_1 + v_2$, with

$$\begin{aligned} v_1 &\in \mathcal{H}(V), \\ v_2 &\in \mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V). \end{aligned}$$

It follows that if $F \in \mathcal{H}^\perp(V)$ then u satisfies (3.2) for all $v \in \mathring{H}^m(V, E)$, as desired.

Finally, since for any section $F \in H^{-m}(V, E)$ “orthogonal” to $\mathcal{H}(V)$ there is a unique solution to Problem 3.1 in

$$\mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V),$$

the estimate (3.1) follows from the Open Map Theorem. □

We are now in a position to derive a Hodge decomposition for the Dirichlet problem in V .

Theorem 3.3 *There are bounded linear operators*

$$\begin{aligned} H : H^{-m}(V, E) &\rightarrow \mathcal{H}(V), \\ G : H^{-m}(V, E) &\rightarrow \mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V) \end{aligned}$$

such that

- 1) H is the $L^2(V, E)$ -orthogonal projection onto the space $\mathcal{H}(V)$, with a kernel $K_H(x, y) = \sum_j h_j(x) \otimes *_E h_j(y)$ where (h_j) is an orthogonal basis of $\mathcal{H}(V)$;
- 2) $AH = 0$ and $GH = HG = 0$;
- 3)

$$\begin{aligned} G\Delta u &= u - Hu \quad \text{for all } u \in \mathring{H}^m(V, E), \\ \Delta GF &= F - HF \quad \text{for all } F \in H^{-m}(V, E). \end{aligned}$$

Proof. As already mentioned in the proof of Lemma 3.2, $\mathcal{H}(V)$ is a finite-dimensional subspace of $C^\infty(X, E)$. Denote H the $L^2(V, E)$ -orthogonal projection onto $\mathcal{H}(V)$. Fix an orthogonal basis (h_j) for $\mathcal{H}(V)$. Then H has the kernel

$$K_H(x, y) = \sum_j h_j(x) \otimes *_E h_j(y),$$

because

$$(HF)(x) = \sum_j \left(\int_V (F(y), h_j(y))_y dy \right) h_j(x)$$

for all $F \in L^2(V, E)$. Since H is a smoothing operator it extends to all of $H^{-m}(V, E)$, too, by

$$(HF)(x) = \langle K_H(x, \cdot), F \rangle_V,$$

for $x \in V$. Clearly,

$$H : H^{-m}(V, E) \rightarrow \mathcal{H}(V) \hookrightarrow \mathring{H}^m(V, E)$$

is bounded and $AH = 0$.

Pick $F \in H^{-m}(V, E)$. Since $K_H(x, y)^* = K_H(y, x)$ we get

$$\begin{aligned} \int_V (F - HF, v)_x dx &= \int_V (F - HF, Hv)_x dx \\ &= \int_V (HF - H^2F, v)_x dx \\ &= \int_V (HF - HF, v)_x dx \\ &= 0 \end{aligned}$$

for all $v \in \mathcal{H}(V)$, i.e.,

$$F - HF \in \mathcal{H}^\perp(V).$$

Therefore, Lemma 3.2 implies that there exists a solution $u \in \mathring{H}^m(V, E)$ to $\Delta u = F - HF$ in V . Setting

$$GF = u - Hu$$

we obtain

$$F = HF + \Delta GF$$

for all $F \in H^{-m}(V, E)$.

As $u - Hu \in \mathcal{H}^\perp(V)$ we see from (3.1) that

$$G : H^{-m}(V, E) \rightarrow \mathring{H}^m(V, E) \cap \mathcal{H}^\perp(V)$$

is bounded. By definition, $HGF = Hu - H^2u = 0$ and $GHF = 0$.

On the other hand, we easily obtain the $L^2(V, E)$ -orthogonal decomposition

$$\begin{aligned} u &= Hu + (u - Hu) \\ &= Hu + G\Delta u \end{aligned}$$

for all $u \in \mathring{H}^m(V, E)$. This completes the proof. \square

When restricted to $L^2(V, E)$, the operator G is selfadjoint. In fact, given any $F, v \in H^{-m}(V, E)$, we have

$$\begin{aligned} (GF, v) &= (GF, Hv + \Delta Gv) \\ &= (GF, \Delta Gv) \\ &= (\Delta GF, Gv) \\ &= (F, Gv), \end{aligned}$$

(\cdot, \cdot) meaning the scalar product in $L^2(V, E)$. Hence it follows that the Schwartz kernel of G ,

$$K_G(\cdot, \cdot) \in \mathring{H}^m(V, E) \otimes \mathring{H}^m(V, E^*) \hookrightarrow \mathcal{D}'(V \times V, E \otimes E^*),$$

is Hermitian, i.e., $K_G(x, y)^* = K_G(y, x)$ for all $x, y \in V$.

Lemma 3.4 *The operator $T = GA^*$ extends to a continuous linear mapping*

$$L^2(V, F) \rightarrow \mathring{H}^m(V, E).$$

Proof. For any fixed $f \in L^2(V, F)$, the integral

$$\int_V (f, Av)_x dx$$

defines a continuous linear functional on $\mathring{H}^m(V, E)$. Hence, the (formal) adjoint A^* extends to a mapping $L^2(V, F) \rightarrow H^{-m}(V, E)$, which is obviously continuous. Since G maps $H^{-m}(V, E)$ continuously to $\mathring{H}^m(V, E)$, the lemma follows. \square

As is easy to check by Stokes' formula, the Schwartz kernel of T is

$$K_T(x, y) = (A^*(y, D))' K_G(x, y),$$

the 'prime' meaning the transposed operator.

Using T , we may rewrite the Hodge decomposition of Theorem 3.3 in the form

$$u = Hu + T Au \quad (3.4)$$

over V , for each $u \in \mathring{H}^m(V, E)$.

We now introduce the Hermitian form

$$h(u, v) = \int_V (Hu, Hv)_x dx + \int_V (Au, Av)_x dx$$

defined for $u, v \in \mathring{H}^m(V, E)$

Theorem 3.5 *The Hermitian form $h(\cdot, \cdot)$ is a scalar product in $\mathring{H}^m(V, E)$ defining a norm equivalent to the original one. The operator H is also an orthogonal projection from $\mathring{H}^m(V, E)$ onto $\mathcal{H}(V)$ with respect to $h(\cdot, \cdot)$. Moreover,*

$$h(Tf, u) = \int_V (f, Au)_x dx$$

for all $f \in L^2(V, F)$ and $u \in \mathring{H}^m(V, E)$.

Proof. The coefficients of A are C^∞ up to the boundary of X , and so $Au \in L^2(V, F)$ for all $u \in \mathring{H}^m(V, E)$. Moreover, it follows from (3.4) that $h(u, u) = 0$ implies $u \equiv 0$ in X . Hence $h(\cdot, \cdot)$ is a scalar product on $\mathring{H}^m(V, E)$.

Since H is a smoothing operator, the original norm of $\mathring{H}^m(V, E)$ is not weaker than $\sqrt{h(\cdot, \cdot)}$.

Further, (3.4) and Lemma 3.4 show that there exists a constant $c > 0$ such that

$$\|u\|_{H^m(V, E)} \leq c (\|Hu\|_{H^m(V, E)} + \|Au\|_{L^2(V, F)})$$

for all $u \in \mathring{H}^m(V, E)$.

On the other hand, since H is a finite rank operator, there is a constant $C > 0$ such that

$$\|Hu\|_{H^m(V, E)} \leq C \|Hu\|_{L^2(V, E)}$$

for all $u \in \mathring{H}^m(V, E)$. This proves the equivalence of the topologies.

Suppose $f \in C_{\text{comp}}^\infty(V, F)$ and $u \in \mathring{H}^m(V, E)$. By Theorem 3.3, we get $HTf = 0$. Moreover,

$$\begin{aligned} \int_V (HA^*f, v)_x dx &= \int_V (f, AHv)_x dx \\ &= 0 \end{aligned}$$

for all $v \in L^2(V, E)$, whence $HA^*f = 0$. Thus,

$$\begin{aligned} h(Tf, u) &= \int_V (AG(A^*f), Au)_x dx \\ &= \int_V (\Delta G(A^*f), u)_x dx \\ &= \int_V (A^*f - H(A^*f), u)_x dx \\ &= \int_V (f, Au)_x dx. \end{aligned}$$

As $C_{\text{comp}}^\infty(V, F)$ is dense in $L^2(V, F)$, we obtain the desired assertion on the integral T .

Finally, for any $u, v \in \mathring{H}^m(V, E)$, we have

$$\begin{aligned} h(Hu, v) &= h(u, v) - h(TAu, v) \\ &= h(u, v) - \int_V (Au, Av)_x dx \\ &= \int_V (Hu, Hv)_x dx, \end{aligned}$$

i.e., H is a selfadjoint operator in $\mathring{H}^m(V, E)$ with respect to the scalar product $h(\cdot, \cdot)$, and $H^2 = H$, as desired. □

4 Green formulas on manifolds with cracks

In this section we discuss Green formulas for sections of E on open subsets of V . To this end, we choose a Green operator $G_A(\cdot, \cdot)$ for A on X , cf. [9, 9.2.1]. Given an oriented hypersurface $S \subset X$, we denote $[S]^A$ the kernel over $X \times X$ defined by

$$\langle [S]^A, g \otimes u \rangle_{X \times X} = \int_S G_A(g, u)$$

for all $g \in C^\infty(X, F^*)$ and $u \in C^\infty(X, E)$ whose supports meet each other in a compact set.

In particular, the kernel $[\partial V]^A$ is supported by the hypersurface $\partial X \cup \sigma$. However, σ , if regarded as a part of the boundary of V , has two sides in X with opposite orientations. When applied to sections g and u whose derivatives up to order $m - 1$ are continuous in a neighbourhood of σ , the kernel $[\partial V]^A$ does not include any integration over σ because the integrals over the sides with opposite orientations cancel. In general, the continuity up to the boundary in V does not assume that the limit values from both sides of σ coincide in the interior of σ on S . Hence, $[\partial V]^A$ actually includes, along with the integral over ∂X , the integral over σ of the difference of the limit values of $G_A(g, u)$ on S .

Away from the singularities of V , i.e., $\partial\sigma$, the Green operator G behaves like the Green function of an elliptic boundary value problem, cf. [5]. The edge $\partial\sigma$ is well known to cause additional singularities of the kernel of G on $(V \times \partial\sigma) \cup (\partial\sigma \times V)$.

Given any section $u \in H^m(V, E)$ vanishing in a neighbourhood of $\partial\sigma$, we set

$$\begin{aligned} (Mu)(x) &= -GA^*([\partial V]^A u) \\ &= -\int_{\partial V} G_A(K_T(x, y), u(y)) \end{aligned}$$

for $x \in V$.

Theorem 4.1 *As defined above, the operator M extends to a continuous mapping of $H^m(V, E)$, and*

$$u = Hu + TAu + Mu \tag{4.1}$$

for all $u \in H^m(V, E)$.

Proof. Given any $u \in H^m(V, E)$, we define Mu from the equality (4.1), namely

$$Mu = u - Hu - TAu.$$

Note that H is a smoothing operator in the sense that it extends naturally to a continuous mapping

$$H^{-\infty}(V, E) \rightarrow \mathring{H}^{\infty}(V, E),$$

where $\mathring{H}^{\infty}(V, E)$ is the projective limit of the family $\mathring{H}^s(V, E)$, $s \in \mathbb{Z}_+$, and $H^{-\infty}(V, E)$ the dual space under the pairing induced from $L^2(V, E)$. Hence it follows, by Lemma 3.4, that M is a well-defined continuous mapping of $H^m(V, E)$.

We shall have established the theorem if we prove that the operator M defined from (4.1) is actually an appropriate extension of the operator M

given before Theorem 4.1. This is an easy consequence of Stokes' formula. Indeed, pick a $u \in H^m(V, E)$ vanishing near $\partial\sigma$. Combining Stokes' formula and Theorem 3.3, we get

$$\begin{aligned} (u - Hu - T Au, v)_{L^2(V, E)} &= (u, v - Hv)_{L^2(V, E)} - (Au, AGv)_{L^2(V, F)} \\ &= (u, v - Hv - \Delta Gv)_{L^2(V, E)} - \int_{\partial V} G_A(*_F(AGv), u) \\ &= (-T([\partial V]^A u), v)_{L^2(V, E)} \end{aligned}$$

for all $v \in C_{\text{comp}}^\infty(V, E)$. This shows that $Mu = -T([\partial V]^A u)$ in (the interior of) V , as desired. \square

We now consider the inhomogeneous Dirichlet problem for the Laplacian Δ on V .

To this end, we first give a rigorous meaning to the boundary condition $t(u) = u_0$ on ∂V . If $\partial\sigma$ is sufficiently smooth, t induces a topological isomorphism

$$\frac{H^m(V, E)}{\mathring{H}^m(V, E)} \xrightarrow{\cong} \oplus_{j=0}^{m-1} H^{m-m_j-1/2}(\partial V, F_j),$$

which is due to (2.1). Hence we can more generally interpret t as the quotient mapping

$$t : H^m(V, E) \rightarrow \frac{H^m(V, E)}{\mathring{H}^m(V, E)}, \quad (4.2)$$

the quotient on the right substituting the space of Dirichlet data on ∂V . We make use of the Hilbert structure in $H^m(V, E)$ to construct a continuous right inverse t^{-1} for t .

Problem 4.2 *Given $F \in H^{-m}(V, E)$ and $u_0 \in H^m(V, E)/\mathring{H}^m(V, E)$, find a section $u \in H^m(V, E)$ such that*

$$\begin{cases} \Delta u &= F & \text{in } V, \\ t(u) &= u_0 & \text{on } \partial V. \end{cases}$$

Lemma 4.3 *Problem 4.2 is solvable if and only if $F \in \mathcal{H}^\perp(V)$. Moreover, for each $F \in \mathcal{H}^\perp(V)$,*

$$u = GF + M(t^{-1}u_0)$$

is the solution to Problem 4.2 belonging to $H^m(V, E) \cap \mathcal{H}^\perp(V)$ and thus satisfying

$$\|u\|_{H^m(V, E)} \leq c \left(\|F\|_{H^{-m}(V, E)} + \|u_0\|_{\frac{H^m(V, E)}{\mathring{H}^m(V, E)}} \right). \quad (4.3)$$

Proof. The necessity of the condition $F \in \mathcal{H}^\perp(V)$ is obvious. What is left is to show that under this condition $u = GF + M(t^{-1}u_0)$ is the solution to Problem 4.2 in $H^m(V, E) \cap \mathcal{H}^\perp(V)$.

Indeed, Theorem 3.3 shows that $GF \in \mathring{H}^m(V, E)$ is “orthogonal” to $\mathcal{H}(M)$ and satisfies $\Delta(GF) = F$.

On the other hand, given any Dirichlet data u_0 , we find a $U \in H^m(V, E)$ such that $t(U) = u_0$ on ∂V . Note that MU is actually independent of the particular choice of U , for if $U', U'' \in H^m(V, E)$ satisfy

$$\begin{aligned} t(U') &= u_0, \\ t(U'') &= u_0 \end{aligned}$$

then $U' - U'' \in \mathring{H}^m(V, E)$ whence

$$\begin{aligned} MU' &= MU'' + M(U' - U'') \\ &= MU'' + (U' - U'') - H(U' - U'') - G\Delta(U' - U'') \\ &= MU'', \end{aligned}$$

the last equality being a consequence of Theorem 3.3. Using Theorem 4.1 we get

$$\begin{aligned} \Delta MU &= \Delta(U - HU - G\Delta U) \\ &= \Delta U - (\Delta U - H\Delta U) \\ &= 0 \end{aligned}$$

and

$$\begin{aligned} t(MU) &= t(U - HU - G\Delta U) \\ &= t(U) \\ &= u_0. \end{aligned}$$

Finally, the section MU is “orthogonal” to $\mathcal{H}(V)$ because so are both $U - HU$ and $G\Delta U$.

Summarising we conclude that $u = GF + MU$ gives a canonical solution to Problem 4.2, as desired. The estimate (4.3) is a consequence of the Open Map Theorem. \square

Let D be a relatively compact domain (i.e. open connected subset) in \mathring{X} with a smooth boundary ($S = \partial D$) containing σ .

For

$$\begin{aligned} u &\in H^m(D, E), \\ f &\in L^2(D, F), \end{aligned}$$

we consider the integrals

$$\begin{aligned} H_D u &= H(\chi_D u), \\ T_D f &= T(\chi_D f), \\ M_D u &= -T([\partial D]^A u) \end{aligned}$$

in V , where χ_D is the characteristic function of D in X . Analysis similar to that in the proof of Theorem 4.1 actually shows that

$$\chi_D u = H_D u + T_D A u + M_D u \quad (4.4)$$

over V , for every $u \in H^m(D, E)$.

Lemma 4.4 *As defined above, the integrals H_D , T_D and M_D induce bounded operators*

$$\begin{aligned} H_D &: H^m(D, E) \rightarrow H^m((D, \sigma), E), \\ T_D &: L^2(D, F) \rightarrow H^m((D, \sigma), E), \\ M_D &: H^m(D, E) \rightarrow H^m(D, E). \end{aligned}$$

Proof. We first observe that the space $H^m((D, \sigma), E)$ coincides with the restriction of $\mathring{H}^m(V, E)$ to D .

Since H extends to a continuous mapping $H^{-\infty}(V, E) \rightarrow \mathcal{H}(V)$, the boundedness of H_D is clear.

Suppose $f \in L^2(D, F)$. Then $\chi_D f$ is naturally regarded as the extension of f to a section in $L^2(X, F)$ by zero. We have $T_D f = T(\chi_D f)$, and so the mapping $T_D : L^2(D, F) \rightarrow H^m((D, \sigma), E)$ is continuous, which is due to Lemma 3.4.

Finally, in order to complete the proof it is sufficient to invoke the equality $M_D = \text{Id} - H_D - T_D A$ in D .

□

5 Examples

Example 5.1 Let X be a bounded domain with smooth boundary in \mathbb{R}^n , $n > 1$, and A an operator with injective symbol in a neighbourhood \tilde{X} of \bar{X} . Assume that A fulfills the uniqueness condition for the Cauchy problem in the small on \tilde{X} . Write G for the Green function of the Dirichlet problem for the Laplacian $\Delta = A^* A$ in X . In [3], a scalar product $h_D(\cdot, \cdot)$ on $H^m(D, E)$ is constructed, such that the corresponding norm is equivalent to the original one and the operator T_D is adjoint to $A : H^m(D, E) \rightarrow L^2(D, F)$ with respect to $h_D(\cdot, \cdot)$, i.e.

$$h_D(T_D f, v) = \int_D (f, A v)_x dx$$

for all $f \in L^2(D, F)$ and $v \in H^m(D, F)$. This implies that the iterations of the double layer potential M_D in $H^m(D, F)$ converge to the projection onto the subspace $H^m(D, E) \cap \mathcal{S}_A(D)$. This case corresponds to the Hodge decomposition for the Dirichlet problem in X with empty crack σ and $\mathcal{H}(V)$ being trivial. \square

Recall that $H^m((D, \sigma), E)$ just amounts to the subspace of $H^m(D, E)$ consisting of all u with $t(u) = 0$ on σ .

Example 5.2 Under the assumptions of Example 5.1, let moreover X have a crack along a closed piece σ of a smooth hypersurface in X . We denote G the Green function of the Dirichlet problem for the Laplacian Δ in $V = X \setminus \sigma$. In our paper [8], a scalar product $h_D(\cdot, \cdot)$ on $H^m((D, \sigma), E)$ is constructed, defining an equivalent topology on this space and such that the operator T_D is actually adjoint to $A : H^m((D, \sigma), E) \rightarrow L^2(D, F)$ with respect to $h_D(\cdot, \cdot)$, i.e.,

$$h_D(T_D f, v) = \int_D (f, Av)_x dx$$

for all $f \in L^2(D, F)$ and $v \in H^m((D, \sigma), E)$. When combined with a general result of functional analysis, this implies that the limit of iterations M_D^N in the strong operator topology of $\mathcal{L}(H^m((D, \sigma), E))$ is equal to zero. This case corresponds to the Hodge decomposition for the Dirichlet problem in X with a crack along σ and $H = 0$. \square

In the next section we will prove similar results for the integrals T_D and M_D in our more general setting.

6 Construction of the scalar product $h_D(\cdot, \cdot)$

We first apply Lemma 4.3 to $X \setminus D$, a C^∞ manifold with boundary. Namely, write $\mathcal{S}_\Delta^m(\hat{X} \setminus D)$ for the subspace of $H^m(X \setminus D, E)$ consisting of all u , such that $\Delta u = 0$ in the interior of $X \setminus D$ and $t(u) = 0$ on ∂X . By Lemma 4.3, we get a topological isomorphism

$$\mathcal{S}_\Delta^m(\hat{X} \setminus D) \cap \mathcal{H}^\perp(X \setminus D) \xrightarrow{t_+} \oplus_{j=0}^{m-1} H^{m-m_j-1/2}(\partial D, F_j)$$

given by $u \mapsto t(u)|_{\partial D}$. Finally, composing the inverse t_+^{-1} with the trace operator

$$H^m(D, E) \xrightarrow{t_-} \oplus_{j=0}^{m-1} H^{m-m_j-1/2}(\partial D, F_j)$$

we arrive at a continuous linear mapping

$$H^m(D, E) \ni u \mapsto \mathcal{E}(u) \in \mathcal{S}_\Delta^m(\hat{X} \setminus D) \cap \mathcal{H}^\perp(X \setminus D). \quad (6.1)$$

For $u \in H^m(D, E)$, we now set

$$e(u)(x) = \begin{cases} u(x) & \text{if } x \in D, \\ \mathcal{E}(u)(x) & \text{if } x \in X \setminus \bar{D}. \end{cases}$$

Since $t(\mathcal{E}(u)) = t(u)$ on ∂D , it follows that $e(u) \in H^m(X, E)$. Furthermore, we have

$$e(u) \in \mathring{H}^m(V, E)$$

for all $u \in H^m((D, \sigma), E)$.

Theorem 6.1 *The Hermitian form $h_D(u, v) = h(e(u), e(v))$ is a scalar product in $H^m((D, \sigma), E)$ defining a topology equivalent to the original one.*

Proof. Theorem 3.5 implies the existence of a positive constant c with the property that

$$\begin{aligned} \|u\|_{H^m(D, E)}^2 &\leq \|e(u)\|_{H^m(V, E)}^2 \\ &\leq c h(e(u), e(u)) \end{aligned}$$

for all $u \in H^m((D, \sigma), E)$.

On the other hand,

$$\begin{aligned} h_D(u, u) &\leq C \|e(u)\|_{H^m(V, E)}^2 \\ &\leq 2C (\|u\|_{H^m(D, E)}^2 + \|\mathcal{E}(u)\|_{H^m(X \setminus D, E)}^2) \end{aligned}$$

for all $u \in H^m((D, \sigma), E)$, with C a constant independent of u . Using Lemma 4.3 and the continuity of the trace operator we see that

$$\begin{aligned} \|\mathcal{E}(u)\|_{H^m(X \setminus D, E)} &\leq c \sum_{j=0}^{m-1} \|B_j u\|_{H^{m-m_j-1/2}(\partial D, F_j)} \\ &\leq C \|u\|_{H^m(D, E)} \end{aligned}$$

for all $u \in H^m(D, E)$, the constants c and C need not be the same in different applications. This finishes the proof. \square

Theorem 6.2 *Assume that $u \in H^m(D, E)$ and $f \in L^2(D, F)$. For every $v \in H^m((D, \sigma), E)$, it follows that*

$$\begin{aligned} h_D(T_D f, v) &= \int_D (f, Av)_x dx, \\ h_D((H_D + M_D)u, v) &= \int_{X \setminus D} (A\mathcal{E}(u), A\mathcal{E}(v))_x dx + \int_X (He(u), He(v))_x dx. \end{aligned}$$

Proof. Suppose $f \in C_{\text{comp}}^\infty(D, F)$. Then $T_D f \in \mathring{H}^m(V, E)$. Let us show that

$$e(Tf|_D) = Tf.$$

For this purpose, it is sufficient to check that the restriction of Tf to $X \setminus \bar{D}$ lies in $\mathcal{S}_\Delta^m(\hat{X} \setminus D) \cap \mathcal{H}^\perp(X \setminus D)$.

However, $Tf = G(A^*f)$ and therefore, as we have already seen in the proof of Theorem 3.5,

$$\begin{aligned} \Delta Tf &= A^*f - HA^*f \\ &= A^*f \end{aligned}$$

on X . Since f has a compact support in D we readily deduce that $\Delta Tf = 0$ in $X \setminus \bar{D}$.

Note that $\mathcal{H}(X \setminus D) \subset \mathcal{H}(V)$. Indeed, every element $u \in \mathcal{H}(X \setminus D)$ can be extended by zero from $X \setminus D$ to all of X as a solution to $Au = 0$ on X . Since $G(A^*f)$ is “orthogonal” to $\mathcal{H}(V)$ we conclude that $Tf|_{X \setminus \bar{D}} \in \mathcal{H}^\perp(X \setminus D)$, as desired.

Further, if $v \in H^m((D, \sigma), E)$ then $e(v) \in \mathring{H}^m(V, E)$ and Theorem 3.5 implies

$$\begin{aligned} h_D(T_D f, v) &= h(Tf, e(v)) \\ &= \int_X (f, Ae(v))_x dx \\ &= \int_D (f, Av)_x dx. \end{aligned}$$

Since $C_{\text{comp}}^\infty(D, F)$ is dense in $L^2(D, F)$ and the operator T_D is bounded, this formula actually holds for all $f \in L^2(D, F)$.

Finally, (4.4) implies that

$$\begin{aligned} h_D((H_D + M_D)u, v) &= h_D(u - T_D Au, v) \\ &= \int_{X \setminus D} (A\mathcal{E}(u), A\mathcal{E}(v))_x dx + \int_X (He(u), He(v))_x dx \end{aligned}$$

for all $v \in H^m((D, \sigma), E)$, as desired. □

7 Iterations of potentials

Corollary 7.1 *The operators*

$$\begin{aligned} T_D A &: H^m((D, \sigma), E) \rightarrow H^m((D, \sigma), E), \\ H_D + M_D &: H^m((D, \sigma), E) \rightarrow H^m((D, \sigma), E) \end{aligned}$$

are selfadjoint and non-negative with respect to $h_D(\cdot, \cdot)$, and the norms of $T_D A$ and $H_D + M_D$ do not exceed 1.

Proof. This follows immediately from Theorems 6.1 and 6.2. \square

Similarly to $\mathcal{H}^\perp(V)$, we denote $\mathcal{H}^\perp(D)$ the space of all $F \in H^{-m}(D, E)$ such that

$$\int_D (F, v)_x dx = 0$$

for any $v \in \mathcal{H}(D)$. It is easy to see that $H^m((D, \sigma), E) \cap \mathcal{H}^\perp(D)$ just amounts to the orthogonal complement of $\mathcal{H}(D)$ in $H^m((D, \sigma), E)$ with respect to the scalar product $h_D(\cdot, \cdot)$ thereon. Indeed, we have $\mathcal{H}(D) \hookrightarrow \mathcal{H}(V)$ because every element $v \in \mathcal{H}(D)$ may be extended by zero from D to X as a solution to $Av = 0$ on X . It follows that $\mathcal{E}(v) = 0$ for all $v \in \mathcal{H}(D)$, whence $Ae(v) = 0$ on X and

$$\begin{aligned} h_D(u, v) &= \int_X (He(u), He(v))_x dx \\ &= \int_D (u, v)_x dx, \end{aligned}$$

as desired.

Lemma 4.4 allows one to consider iterations of $T_D A$ and $H_D + M_D$ in the space $H^m((D, \sigma), E)$. Given a closed subspace Σ of $H^m((D, \sigma), E)$, we write π_Σ for the orthogonal projection of $H^m((D, \sigma), E)$ onto Σ with respect to the scalar product $h_D(\cdot, \cdot)$.

Corollary 7.2 *In the strong operator topology in $\mathcal{L}(H^m((D, \sigma), E))$, we have*

$$\begin{aligned} \lim_{N \rightarrow \infty} (T_D A)^N &= \pi_{\ker(H_D + M_D)}, \\ \lim_{N \rightarrow \infty} (H_D + M_D)^N &= \pi_{H^m((D, \sigma), E) \cap \mathcal{S}_A(D)}. \end{aligned}$$

Moreover, in the strong operator topology of $\mathcal{L}(L^2(D, F))$,

$$\lim_{N \rightarrow \infty} (\text{Id} - AT_D)^N = \pi_{\ker T_D}.$$

Proof. It follows from Corollary 7.1 that

$$\begin{aligned} \lim_{N \rightarrow \infty} (T_D A)^N &= \pi_{\ker(\text{Id} - T_D A)}, \\ \lim_{N \rightarrow \infty} (H_D + M_D)^N &= \pi_{\ker(\text{Id} - H_D - M_D)}, \\ \lim_{N \rightarrow \infty} (\text{Id} - AT_D)^N &= \pi_{\ker AT_D} \end{aligned}$$

in the strong operator topology of $\mathcal{L}(H^m((D, \sigma), E))$ or $\mathcal{L}(L^2(D, F))$, respectively (see, for instance, §2 of [3] or [4] for compact operators). Theorem 6.2 and (4.4) imply

$$\begin{aligned} \ker(\text{Id} - T_D A) &= \ker(H_D + M_D), \\ \ker T_D A &= H^m((D, \sigma), E) \cap \mathcal{S}_A(D), \\ \ker AT_D &= \ker T_D, \end{aligned}$$

showing the corollary. \square

Obliviously, if the coefficients of A are real analytic and σ has at least one interior point on ∂D then $H^m((D, \sigma), E) \cap \mathcal{S}_A(D) = \{0\}$. If moreover every connected component of $X \setminus \bar{D}$ meets the boundary of V , i.e., $\partial X \cup \sigma$, then $H_D = 0$ and

$$\ker M_D = \mathring{H}^m(D, E).$$

Indeed, according to Theorem 6.2, if $u \in H^m((D, \sigma), E)$ and $M_D u = 0$ then $A\mathcal{E}(u) = 0$ in $X \setminus \bar{D}$ and $t(\mathcal{E}(u)) = 0$ on $\partial X \cup \sigma$. Hence it follows that $\mathcal{E}(u) \equiv 0$ in $X \setminus \bar{D}$, and so $t(\mathcal{E}(u)) = 0$ on ∂D . From this we conclude that $t(u) = 0$ on ∂D whence $u \in \mathring{H}^m(D, E)$. Conversely, if $u \in \mathring{H}^m(D, E)$ then $M_D u = 0$, as desired.

Theorem 7.3 *In the strong operator topology of $\mathcal{L}(H^m((D, \sigma), E))$, we have*

$$\text{Id} = H_D + \pi_{\ker(H_D + M_D)} + \sum_{\nu=0}^{\infty} (T_D A)^\nu M_D, \quad (7.1)$$

$$\text{Id} = \pi_{H^m((D, \sigma), E) \cap \mathcal{S}_A(D)} + \sum_{\nu=0}^{\infty} (H_D + M_D)^\nu T_D A. \quad (7.2)$$

Moreover, in the strong operator topology of $\mathcal{L}(L^2(D, F))$,

$$\text{Id} = \pi_{\ker T_D} + \sum_{\nu=0}^{\infty} A (H_D + M_D)^\nu T_D. \quad (7.3)$$

Proof. Write

$$\text{Id} = (\text{Id} - AT_D)^N + \sum_{\nu=0}^{N-1} (\text{Id} - AT_D)^\nu AT_D, \quad (7.4)$$

for every $N = 1, 2, \dots$. It is easily seen from (4.4) that

$$\begin{aligned} (\text{Id} - AT_D)^\nu AT_D &= A (\text{Id} - T_D A)^\nu T_D \\ &= A (H_D + M_D)^\nu T_D. \end{aligned}$$

Using Corollary 7.2 we can pass to the limit in (7.4), when $N \rightarrow \infty$, thus obtaining (7.3). The proofs for (7.1) and (7.2) are similar. \square

8 Cauchy problem

We first introduce the space of Cauchy data on σ , for our differential operator A . Since A is given the domain $H^m(D, E)$, the space of zero Cauchy data is $H^m((D, \sigma), E)$. Recall that $H^m((D, \sigma), E)$ is proved to be the restriction of $\overset{\circ}{H}^m(V, E)$ to D .

Similarly to (4.2) we define the space of Cauchy data on σ as the quotient space

$$\frac{H^m(D, E)}{H^m((D, \sigma), E)},$$

t being thought of as the quotient mapping

$$t : H^m(D, E) \rightarrow \frac{H^m(D, E)}{H^m((D, \sigma), E)}. \quad (8.1)$$

Once again we use the Hilbert structure in $H^m(D, E)$ to construct a continuous right inverse t^{-1} for t .

If the boundary of σ on ∂D is sufficiently smooth then the quotient space in (8.1) can be identified with $\oplus_{j=0}^{m-1} H^{m-m_j-1/2}(\sigma, F_j)$.

Consider the following Cauchy problem, for the operator A and the Dirichlet system $(B_j)_{j=0, \dots, m-1}$.

Problem 8.1 *Given $f \in L^2(D, F)$ and $u_0 \in H^m(D, E)/H^m((D, \sigma), E)$, find $u \in H^m(D, E)$ satisfying*

$$\begin{cases} Pu &= f & \text{in } D, \\ t(u) &= u_0 & \text{on } \sigma. \end{cases}$$

This problem is ill-posed if σ is different from the whole boundary. Using Theorem 7.3 we obtain approximate solutions to the problem. To this end, we observe that

$$\frac{H^m(V, E)}{\overset{\circ}{H}^m(V, E)} \hookrightarrow \frac{H^m(D, E)}{H^m((D, \sigma), E)}$$

is a well-defined mapping “onto”, which substitutes restriction of sections over ∂V to σ . Pick a $U \in H^m(V, E)$ such that $t(U) = u_0$ on σ . Lemma 4.3 yields that $MU \in H^m(V, E)$ satisfies $\Delta MU = 0$ in V and $t(MU) = u_0$ on σ , the last property being sufficient. Problem 8.1 thus reduces to that with zero boundary conditions.

Problem 8.2 *Given any $f \in L^2(D, F)$, find a section $u \in H^m((D, \sigma), E)$ such that $Au = f$ in D .*

Note that for the problem to be solvable it is necessary that $f \perp \ker T_D$. Indeed,

$$\begin{aligned} \int_D (f, g)_x dx &= \int_D (Au, g)_x dx \\ &= h_D(u, T_D g) \\ &= 0 \end{aligned}$$

for all $g \in L^2(D, F)$ satisfying $T_D g = 0$, the second equality being due to Theorem 6.2.

Theorem 8.3 *Suppose $f \in L^2(D, F)$. Problem 8.2 is solvable if and only if $f \perp \ker T_D$ and the series*

$$Rf = \sum_{\nu=0}^{\infty} (H_D + M_D)^\nu T_D f$$

converges in $H^m((D, \sigma), E)$. Moreover, if these conditions hold then Rf is a solution to Problem 8.2.

Proof. As mentioned above, the necessity follows from Theorems 6.1 and 7.3.

Conversely, let both conditions of the theorem be fulfilled. Then (7.3) implies

$$f = \sum_{\nu=0}^{\infty} A (H_D + M_D)^\nu T_D f.$$

Since the series Rf converges in $H^m((D, \sigma), E)$ we conclude that $f = ARf$, as desired. □

In the case considered in Example 5.2 a similar result has been proved in [8].

Corollary 7.2 shows that the solution $u = Rf$ lies in the orthogonal complement of the subspace $H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$ in $H^m((D, \sigma), E)$ with respect to the scalar product $h_D(\cdot, \cdot)$. Clearly, Problem 8.2 possesses at most one solution belonging to this orthogonal complement. The partial sums $R_N f$ of the series Rf may be regarded as approximate solutions to Problem 8.2, provided that $f \perp \ker T_D$. In fact, it follows easily from Corollary 7.2 and Theorem 7.3 that $R_N f$ belongs to the orthogonal complement in question, for each $N = 0, 1, \dots$, and

$$\lim_{N \rightarrow \infty} \|f - (\pi_{\ker T_D} f + AR_N f)\|_{L^2(D, F)} = 0$$

for all $f \in L^2(D, F)$. Indeed,

$$\|f - (\pi_{\ker T_D} f + AR_N f)\|_{L^2(D, F)} = \left\| \sum_{\nu=N+1}^{\infty} A M_D^\nu T_D f \right\|_{L^2(D, F)},$$

and the last expression is the rest of a converging series.

If A is included into an elliptic complex

$$C_{\text{loc}}^\infty(X, E) \xrightarrow{A} C_{\text{loc}}^\infty(X, F) \xrightarrow{B} C_{\text{loc}}^\infty(X, G)$$

then the condition $f \perp \ker T_D$ in Theorem 8.3 may be replaced by

- 1) $Bf = 0$ in D ;
- 2) $f \perp \ker T_D \cap \mathcal{S}_B(D)$.

Write

$$n(g) = \oplus_{j=0}^{m-1} *_{F_j}^{-1} C_j *_F (g)$$

for the formal adjoint of t with respect to the Green formula for A in D , cf. [9, 9.2.3]. Set

$$\mathcal{H}^1(D, \sigma) = \{g \in L^2(D, F) : A^*g = 0, Bg = 0, \text{ and } n(g) = 0 \text{ on } \partial D \setminus \sigma\}.$$

We call $\mathcal{H}^1(D, \sigma)$ the *harmonic space* in the Cauchy problem with data on σ . By the ellipticity assumption, the elements of $\mathcal{H}^1(D, \sigma)$ are of class C^∞ in D .

Lemma 8.4 $\ker T_D \cap \mathcal{S}_B(D) = \mathcal{H}^1(D, \sigma)$.

Proof. Let $g \in \ker T_D \cap \mathcal{S}_B(D)$. From Theorem 6.2 it follows that $A^*g = 0$ in the sense of distributions on D . By the ellipticity of $B \oplus A^*$ we conclude that $g \in C_{\text{loc}}^\infty(D, F)$.

We next claim that $n(g) = 0$ weakly on $\partial D \setminus \sigma$. To prove this, we denote by D_ε the set of all $x \in D$ such that $\text{dist}(x, \partial D) > \varepsilon$. For $\varepsilon > 0$ small enough, D_ε is also a domain with C^∞ boundary. We shall have established the equality $n(g) = 0$ on $\partial D \setminus \sigma$ if we show that

$$\lim_{\varepsilon \rightarrow 0} \int_{\partial D_\varepsilon} (t(u), n(g))_x ds_\varepsilon = 0$$

for all $u \in C^\infty(\bar{D}, E)$ vanishing near σ . Here, ds_ε is the area element of the surface ∂D_ε .

Since g is C^∞ in D , we get

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \int_{\partial D_\varepsilon} (t(u), n(g))_x ds_\varepsilon &= \lim_{\varepsilon \rightarrow 0} \int_{D_\varepsilon} (Au, g)_x dx \\ &= \int_D (Au, g)_x dx \\ &= h_D(u, T_D g) \\ &= 0, \end{aligned}$$

the first equality being due to Stokes' formula and the equality $A^*g = 0$, the second equality being a consequence of the fact that $g \in L^2(D, F)$, and the third one being due to Theorem 6.2. We have thus proved that $\ker T_D \cap \mathcal{S}_B(D)$ is a subset of $\mathcal{H}^1(D, \sigma)$.

Let us prove the opposite inclusion. Pick a $g \in \mathcal{H}^1(D, \sigma)$. By ellipticity we conclude that $g \in C_{\text{loc}}^\infty(D, F)$. For every $u \in C_{\text{loc}}^\infty(\bar{D}, E)$ vanishing near σ , we have

$$\begin{aligned} h_D(u, T_D g) &= \lim_{\varepsilon \rightarrow 0} \int_{D_\varepsilon} (Au, g)_x dx \\ &= \lim_{\varepsilon \rightarrow 0} \int_{\partial D_\varepsilon} (t(u), n(g))_x ds_\varepsilon \\ &= 0. \end{aligned}$$

Since such sections u are dense in $H^m((D, \sigma), E)$, it follows that $T_D g = 0$, as desired. □

It is worth pointing out that the space $\mathcal{H}^1(D, \sigma)$ fails to be finite-dimensional in general.

9 Applications to Zaremba problem

In this section we assume that σ is the closure of an open subset in ∂D with smooth boundary.

Let $H^{-m}((D, \partial D \setminus \sigma), E)$ be the dual space for $H^m((D, \sigma), E)$ with respect to the pairing in $L^2(D, E)$. It coincides with the completion of $C_{\text{comp}}^\infty(D \cup \sigma, E)$ with respect to the norm

$$\|F\|_{H^{-m}((D, \partial D \setminus \sigma), E)} = \sup_{v \in C_{\text{comp}}^\infty(\bar{D} \setminus \sigma, E)} \frac{|\int_D (F, v)_x dx|}{\|v\|_{H^m((D, \sigma), E)}}.$$

Recall that for $s \geq 0$ we write $H^{-s}(\partial D \setminus \sigma, F_j)$ for the dual of $\mathring{H}^s(\partial D \setminus \sigma, F_j)$ with respect to the pairing in $L^2(\partial D \setminus \sigma, F_j)$, cf. Section 3. One can prove that

$$H^{-s}(\partial D \setminus \sigma, F_j) \stackrel{\text{top.}}{\cong} \frac{H^{-s}(\partial D, F_j)}{H_\sigma^{-s}(\partial D, F_j)}$$

where $H_\sigma^{-s}(\partial D, F_j)$ is the subspace of $H^{-s}(\partial D, F_j)$ consisting of the elements with a support in σ .

By the above, the sesquilinear form

$$\int_{\partial D} (u_1, t(v))_x ds$$

is well defined for all

$$\begin{aligned} u_1 &\in \oplus_{j=0}^{m-1} H^{-m+m_j+1/2}(\partial D \setminus \sigma, F_j), \\ v &\in H^m((D, \sigma), E). \end{aligned}$$

We are now in a position to consider the following generalised Zaremba problem in D .

Problem 9.1 *Given*

$$\begin{aligned} F &\in H^{-m}((D, \partial D \setminus \sigma), E), \\ u_1 &\in \oplus_{j=0}^{m-1} H^{-m+m_j+1/2}(\partial D \setminus \sigma, F_j), \end{aligned}$$

find $u \in H^m(D, E)$ such that

$$\begin{cases} \Delta u = F & \text{in } D, \\ t(u) = 0 & \text{on } \sigma, \\ n(Au) = u_1 & \text{on } \partial D \setminus \sigma. \end{cases}$$

The equation $\Delta u = F$ has to be understood in the sense of distributions in D , while the boundary conditions are interpreted in the following weak sense: Find $u \in H^m((D, \sigma), E)$ satisfying

$$\int_D (Au, Av)_x dx = \int_D (F, v)_x dx + \int_{\partial D} (u_1, t(v))_x ds \quad (9.1)$$

for all $v \in H^m((D, \sigma), E)$.

We emphasise that the trace of $n(Au)$ on $\partial D \setminus \sigma$ is not defined for any $u \in H^m((D, \sigma), E)$, because the order of $n \circ A$ is equal to $2m - 1$. To cope with this, a familiar way is to assign an operator L with a dense domain $\text{Dom } L \hookrightarrow H^m((D, \sigma), E)$ to Problem 9.1, such that $n(Au)$ is well defined for all $u \in \text{Dom } L$. In fact, $\text{Dom } L$ is defined to be the completion of $C_{\text{comp}}^\infty(\bar{D} \setminus \sigma, E)$ with respect to the graph norm of $u \mapsto (u, n(Au))$ in $H^m((D, \sigma), E) \oplus \mathfrak{N}$, where

$$\mathfrak{N} = \oplus_{j=0}^{m-1} H^{-m+m_j+1/2}(\partial D \setminus \sigma, F_j).$$

For more details, see Roitberg [5] and elsewhere. Then, (9.1) defines a continuous operator $\text{Dom } L \rightarrow H^{-m}((D, \partial D \setminus \sigma), E) \oplus \mathfrak{N}$ by $Lu = (\Delta u, n(Au))$.

If A is the gradient operator in \mathbb{R}^n , then (9.1) is just the classical Zaremba problem in D .

Lemma 9.2 *Suppose $F = 0$ and $u_1 = 0$. Then $u \in H^m(D, E)$ is a solution to Problem 9.1 if and only if $u \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$.*

Proof. Obviously, any $u \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$ is a solution of Problem 9.1 with $F = 0$ and $u_1 = 0$.

Conversely, let u be a solution to Problem 9.1 with $F = 0$ and $u_1 = 0$. Substituting $v = u$ to (9.1) implies $Au = 0$ whence $u \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$, as desired. \square

Lemma 9.2 shows that Problem 9.1 is not Fredholm in general, for the space $H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$ need not be finite-dimensional.

For any $v \in \mathring{H}^m(V, E)$, the restriction $v|_D$ belongs to $H^m((D, \sigma), E)$. Hence to each $F \in H^{-m}((D, \partial D \setminus \sigma), E)$ we can assign an element $\tilde{F} \in H^{-m}(V, E)$ by

$$(\tilde{F}, v) = (F, v|_D)$$

for all $v \in \mathring{H}^m(V, E)$. We will write \tilde{F} simply $\chi_D F$ when no confusion can arise. Therefore, the integral

$$G(\chi_D F) = \int_D (F, *_E^{-1} K_G(x, \cdot))_y dy$$

defines an element of $H^m((D, \sigma), E)$, for any $F \in H^{-m}((D, \partial D \setminus \sigma), E)$.

Furthermore, since $u \mapsto t(u) \oplus n(Au)$ is a Dirichlet system of order $2m - 1$ on ∂D , for every data $u_1 \in \mathfrak{N}$ there exists a $U \in \text{Dom } L$ with the property that $n(AU) = u_1$ on $\partial D \setminus \sigma$ (see for instance Lemma 9.2.17 of [9]). This means that

$$\int_D (AU, Av)_x dx = \int_D (\Delta U, v)_x dx + \int_{\partial D} (u_1, t(v))_x ds$$

for all $v \in H^m((D, \sigma), E)$. Set

$$\begin{aligned} P_{\text{sl}} u_1(x) &= - \int_{\partial D} G_{A^*}(K_G(x, \cdot), AU) \\ &= \int_{\partial D} (n(AU), t(*_E^{-1} K_G(x, \cdot)))_y ds, \end{aligned}$$

for $x \in D$.

This integral is well defined and it does not depend on the particular choice of U . Indeed, since $\Delta U \in H^{-m}((D, \partial D \setminus \sigma), E)$ we conclude, by Stokes' formula, that

$$\begin{aligned} P_{\text{sl}} u_1 &= GA^*(\chi_D AU) - G(\chi_D \Delta U) \\ &= T_D AU - G(\chi_D \Delta U), \end{aligned}$$

which is in $H^m((D, \sigma), E)$.

Let now $U \in \text{Dom } L$ be such that $n(AU) = 0$ on $\partial D \setminus \sigma$. Then using Theorem 3.3 yields

$$\begin{aligned} \int_X \left(- \int_{\partial D} G_{A^*}(K_G(x, \cdot), AU), v \right)_x dx &= \int_X (GA^* \chi_D AU - G \chi_D \Delta U, v)_x dx \\ &= \int_X (A^* \chi_D AU - \chi_D \Delta U, Gv)_x dx \\ &= \int_D (AU, AGv)_x dx - \int_D (\Delta U, Gv)_x dx \\ &= 0 \end{aligned}$$

for all $v \in C_{\text{comp}}^\infty(X, E)$, because $Gv \in H^m((D, \sigma), E)$. Hence, $P_{\text{sl}}u_1$ is independent of the choice of U .

Theorem 9.3 *Problem 9.1 is solvable if and only if*

1)

$$\int_D (F, v)_x dx + \int_{\partial D} (u_1, t(v))_x ds = 0$$

for all $v \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$;

2) the series

$$R(F, u_1) = \sum_{\nu=0}^{\infty} (H_D + M_D)^\nu (G(\chi_D F) + P_{\text{sl}}u_1)$$

converges in the $H^m(D, E)$ -norm.

If 1) and 2) hold then $R(F, u_1)$ is a solution to Problem 9.1.

Proof. Let Problem 9.1 be solvable and let $u \in H^m((D, \sigma), E)$ be a solution. Then

$$\begin{aligned} T_D Au &= G(\chi_D \Delta u) - \int_{\partial D} G_{A^*}(K_G(x, \cdot), Au) \\ &= G(\chi_D F) + P_{\text{sl}}u_1, \end{aligned}$$

and so the series $R(F, u_1) = RAu$ converges in the $H^m(D, E)$ -norm, which is due to Corollary 7.2.

Conversely, assume that 1) and 2) are fulfilled. Let us prove that the series $R(F, u_1)$ satisfies (9.1). Indeed, by Theorem 6.1

$$\begin{aligned} \int_D (AR(F, u_1), Av)_x dx &= h_D (G(\chi_D F) + P_{\text{sl}}u_1, v) \\ &= h_D (G(\chi_D F) + GA^*(\chi_D AU) - G(\chi_D \Delta U), v) \end{aligned}$$

with a section $U \in \text{Dom } L$ such that $n(AU) = u_1$ on $\partial D \setminus \sigma$.

Using Theorem 3.3 we see that $e(G\tilde{F}) = G\tilde{F}$ for all $\tilde{F} \in H^{-m}(V, E)$ satisfying $\tilde{F} - H\tilde{F} = 0$ in $X \setminus \bar{D}$. We next apply this equality with

$$\tilde{F} = \chi_D F + A^*(\chi_D AU) - \chi_D \Delta U.$$

We have

$$\begin{aligned} \int_X (\tilde{F}, v)_x dx &= \int_D (F - \Delta U, v)_x dx \\ &= \int_D (F, v)_x dx + \int_{\partial D} (n(AU), t(v))_x ds \\ &= 0 \end{aligned}$$

for all $v \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$, the last equality being a consequence of condition 1). Hence it follows readily that $H\tilde{F} = 0$ in V , and so $\tilde{F} - H\tilde{F} = 0$ in $X \setminus \bar{D}$.

Therefore, $e(G\tilde{F}) = G\tilde{F}$ and we get

$$\begin{aligned} \int_D (AR(F, u_1), Av)_x dx &= h(e(G\tilde{F}), e(v)) \\ &= \int_X (AG\tilde{F}, Ae(v))_x dx + \int_X (HG\tilde{F}, He(v))_x dx \\ &= \int_X (\tilde{F}, G\Delta e(v))_x dx \\ &= \int_X (\tilde{F}, e(v) - He(v))_x dx \\ &= \int_D (F - \Delta U, e(v))_x dx + \int_D (AU, Ae(v))_x dx \\ &= \int_D (F, v)_x dx + \int_{\partial D} (n(AU), t(v))_x ds \end{aligned}$$

for all $v \in H^m((D, \sigma), E)$. Here, the fifth equality is due to condition 1) and the fact that $He(v) \in H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$, and the last equality is a consequence of Stokes' formula. We have arrived at (9.1), thus proving the theorem. \square

Corollary 7.2 implies that the solution $R(F, u_1)$ to Problem 9.1 lies in the orthogonal complement of $H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$ in $H^m((D, \sigma), E)$ with respect to the scalar product $h_D(\cdot, \cdot)$. Moreover, $R(F, u_1)$ is the unique solution belonging to this subspace. The partial sums $R_N(F, u_1)$ of the series $R(F, u_1)$ may be regarded as approximate solutions to Problem 9.1, provided that F

and u_1 meet condition 1) of Theorem 9.3. The sequence $R_N(F, u_1)$ has the following property:

$$\begin{aligned} & \left| \int_D (AR_N(F, u_1), Av)_x dx - \int_D (F, v)_y dy - \int_{\partial D} (u_1, t(v))_x ds \right| \\ & \leq c \|M_D^{N+1}(G(\chi_D F) + P_{sl}u_1)\|_{H^m(D, E)} \|v\|_{H^m(D, E)} \end{aligned} \quad (9.2)$$

for all $v \in H^m((D, \sigma), E)$, with c a constant independent of N and v . Indeed, as we have seen above (cf. (7.4)),

$$T_D AR_N(F, u_1) = (G(\chi_D F) + P_{sl}u_1) - M_D^{N+1}(G(\chi_D F) + P_{sl}u_1)$$

whence

$$\begin{aligned} & \int_D (AR_N(F, u_1), Av)_x dx \\ & = h_D(T_D AR_N(F, u_1), v) \\ & = h_D((G(\chi_D F) + P_{sl}u_1) - M_D^{N+1}(G(\chi_D F) + P_{sl}u_1), v) \\ & = \int_D (F, v)_x dx + \int_{\partial D} (u_1, t(v))_x ds - h_D(M_D^{N+1}(G(\chi_D F) + P_{sl}u_1), v). \end{aligned}$$

The scalar product $h_D(\cdot, \cdot)$ defines an equivalent norm, hence the estimate (9.2) holds. Since $G(\chi_D F) + P_{sl}u_1$ is orthogonal to $H^m((D, \sigma), E) \cap \mathcal{S}_A(D)$ we see that

$$\lim_{N \rightarrow \infty} \|M_D^{N+1}(G(\chi_D F) + P_{sl}u_1)\|_{H^m(D, E)} = 0.$$

Of course, if Problem 9.1 is Fredholm then the series $R(F, u_1)$ converges for all data F and u_1 .

In the setting of Example 5.2 such a theorem was proved in [8]. We can also treat the inhomogeneous Zaremba problem.

Problem 9.4 *Given*

$$\begin{aligned} F & \in H^{-m}((D, \partial D \setminus \sigma), E), \\ u_0 & \in \oplus_{j=0}^{m-1} H^{m-m_j-1/2}(\sigma, F_j), \\ u_1 & \in \oplus_{j=0}^{m-1} H^{-m+m_j+1/2}(\partial D \setminus \sigma, F_j), \end{aligned}$$

find $u \in H^m(D, E)$ *such that*

$$\begin{cases} \Delta u &= F & \text{in } D, \\ t(u) &= u_0 & \text{on } \sigma, \\ n(Au) &= u_1 & \text{on } \partial D \setminus \sigma. \end{cases}$$

Indeed, using the potential $M_D t^{-1} u_0$ as in Section 4, we easily reduce it to Problem 9.1.

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